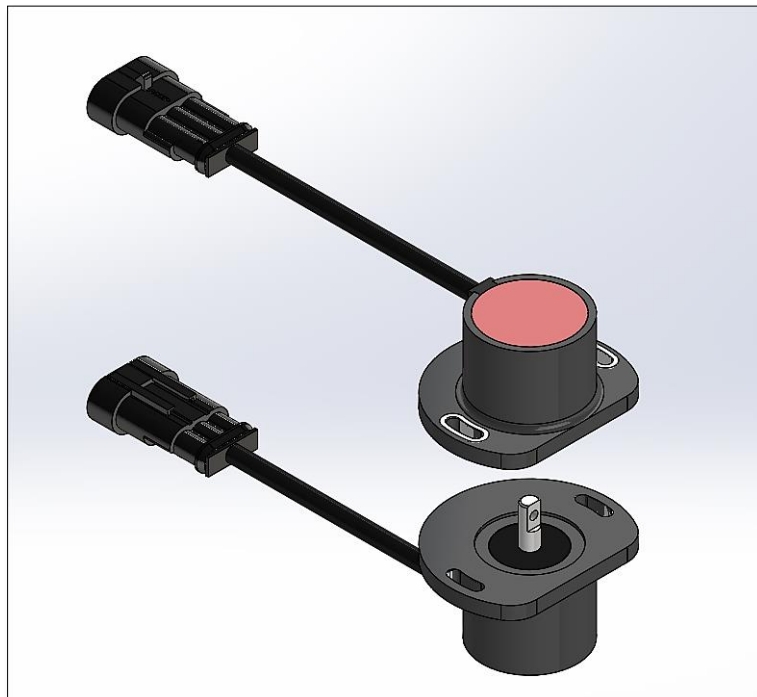
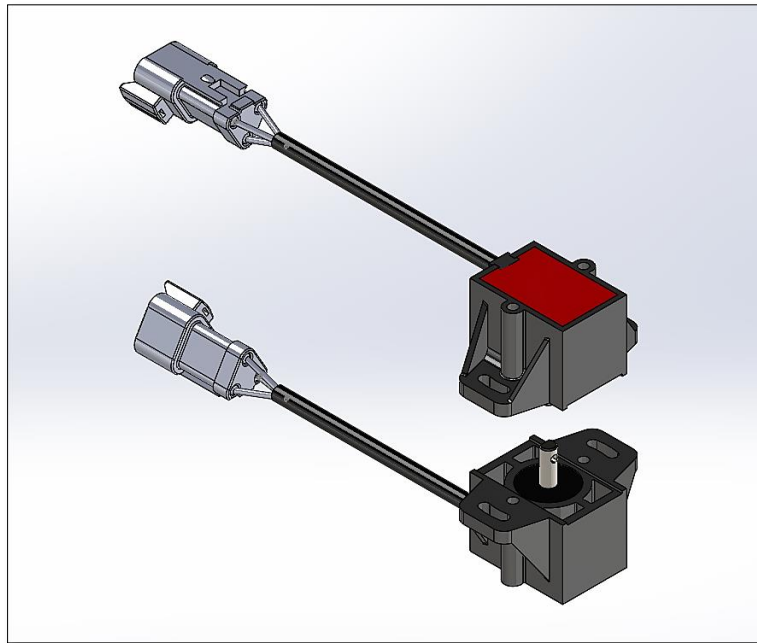


ASBR – Angular Sensor – Solid Shaft Preliminary Datasheet*



*Changes may occur without prior notice.

Angular Sensor



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Specifications

Mechanical characteristics

Shaft diameter *	6mm (0,236 pol)
Recommended fixing screw	M4
Shaft rotation range	Unlimited

* Another option on demand

Electrical characteristics

DC Supply	10 a 30 VDC.
Linear output types*	0,5 V a 4,5 V 0 V a 5 V 4 mA a 20 mA
Output load voltage	Minimum load > 10 K Ω
Output load current	Maximum load < 250 Ω
Power consumption (without load)	< 10 mA
DAC resolution	0,088° (12 bits)
Characteristic curves (signal output profiles)*	Fully Programmable ex.: - Ascending - Descending - Trapezoidal - N module
Electrical protection	Reverse polarity, short circuit and overvoltage
Angular measuring range	18° a 360°

*Another option on demand

Ambiental characteristics

Operational temperature	-10°C to 80°C
Storage temperature	-10°C to 80° C
Ingress Protection code (IP)	IP69
Conformity	RoHS Compliant

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CONFIGURATOR – SOLIF SHAFT

Serie	Code 1	Code 2	Code 3	Code 4	Code 5	Code 6	Code 7	Code 8	Code 9	Code 10	Description
ASBR	Mechanics	Shaft	Signal Increment Direction	Measuring Range Center	Measuring Range	Output	Cable Length	Connector	Special Code	Accessories	
										0 A	No accessories Solid Shaft lever
									0 D *		Standard Curve Double Mirrored Curve (trapezoidal) Another option on demand
								0 N P S *			No connector Deutsch 3 pins, male Delphi 3 pins, male Superseal 3 pins male Another available connector
							1 *				0,1 m Another available length
						A B C *					0,5 V a 4,5 V (Voltage) 0 V a 5,0 V (Voltage) 4-20 mA (Current) Another available amplitude
					018° a 360°						Fully programmable for any range within the limits min. (0-18°) or max. (0-360°)
				000° a 359°							Fully programmable for any specific angle (between 0 and 359°)
			H A								Clockwise – CW Counterclockwise – CCW
	U R	S S									Circular Housing + 6 mm Solid Shaft Rectangular Housing + 6 mm Solid Shaft

* Another option on demand

Codification example

ASBR USA 000 120 A 1S 00 – Angular Sensor with circular housing, 6mm solid shaft (include 3mm recess and drilling), counterclockwise increment, 120° measuring range with center in 0°, 0,5 a 4,5 V output, cable with 0,1 m length and Superseal connector.

ASBR – Angular Sensor – Solid Shaft Preliminary Datasheet*



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DIMENSION – SOLID SHAFT

CODES 1 AND 2 – MECHANICS AND SHAFT

- **U – Circular Housing, solid shaft only (S)**

DIMENSIONS (mm)

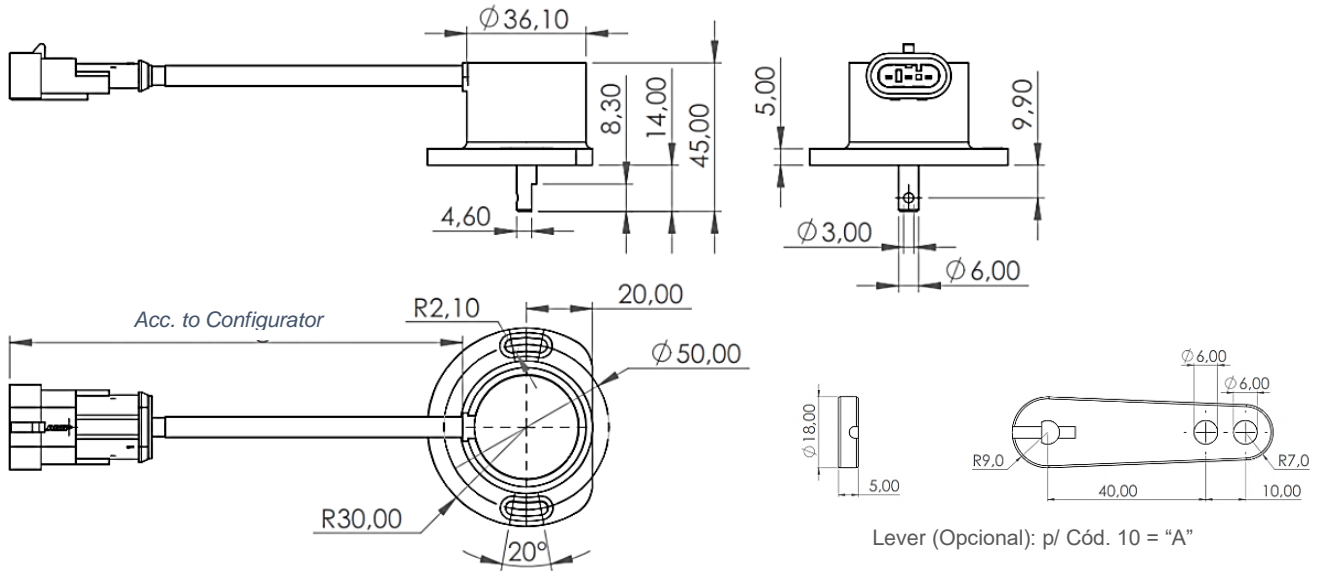


Figure 1 – Circular housing details (solid shaft)

- **R – Rectangular Housing, solid shaft (S)**

DIMENSIONS (mm)

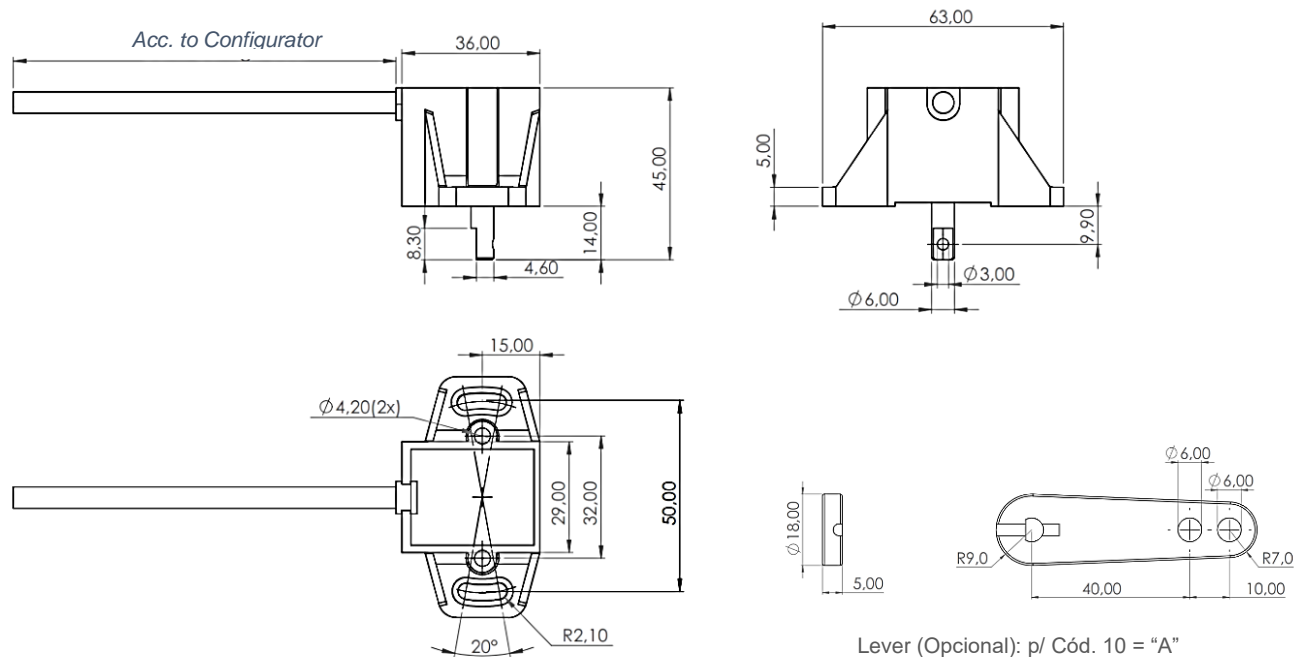


Figure 2 – Rectangular housing details (solid shaft)

MECHANICAL REFERENCE – SOLID SHAFT

CODE 3 – SIGNAL INCREMENT DIRECTION

The **SIGNAL INCREMENT DIRECTION** is the rotational direction (Clockwise: “CW”, or Counterclockwise: “CCW”) for the signal increment range (from the minimal to the maximal amplitude, either in voltage or current), established in the measuring range (useful signal zone, as defined in ‘Code 5’ section).

The **SIGNAL INCREMENT DIRECTION** is referenced in relation to the top view of the sensor (resin side of housing or the opposite view of the shaft), acc. the Fig. 3.

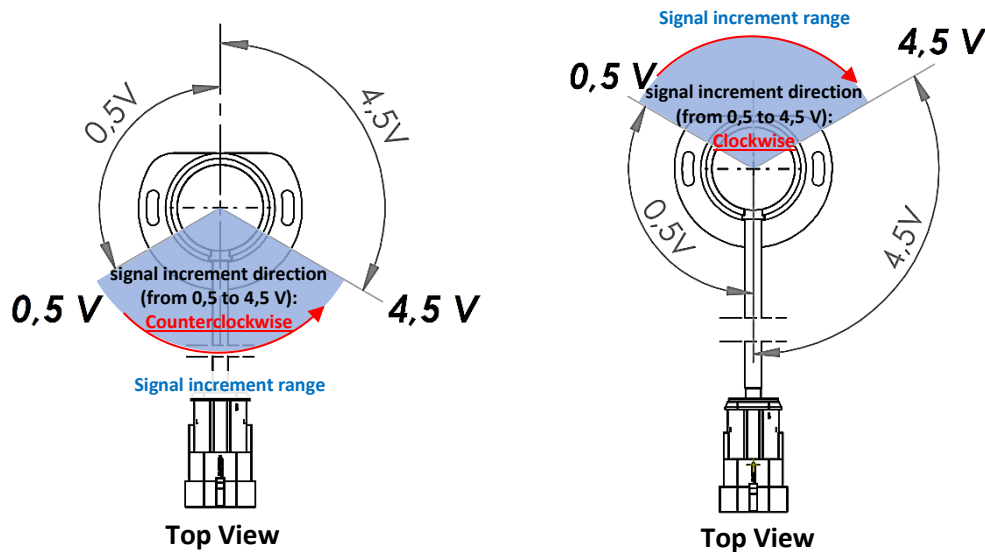


Figure 3 – Signal Increment Direction (examples)

CODE 4 – MEASURING RANGE CENTER

The **MEASURING RANGE CENTER** is a reference for the positioning (*offset*) of the Measuring range (as definition in ‘Code 5’, below), which consists of 2 symmetric segments. The Measuring Range **CENTER** is measured from the origin (line over the sensor cable), clockwise, through the top view of the sensor (see Fig. 4).

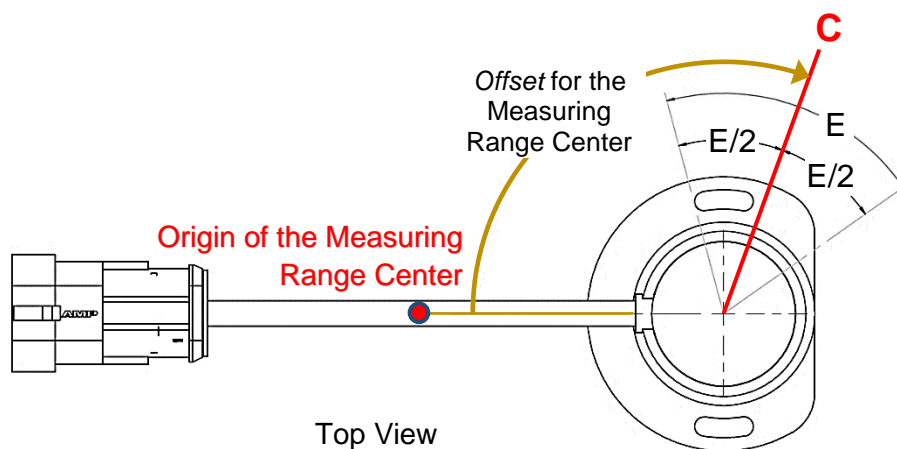


Figure 4 – Representation of Measuring range (E) Center (C)

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In order Measuring Range Center can be a reference for the sensor output signals, it must be related to the **SHAFT** positioning. For the solid-shaft sensor, the referencing is through the milled **RECESS** of shaft, **ORIENTED** to the Measuring Range Center, also referenced from the sensor cable. See examples in Fig. 5.

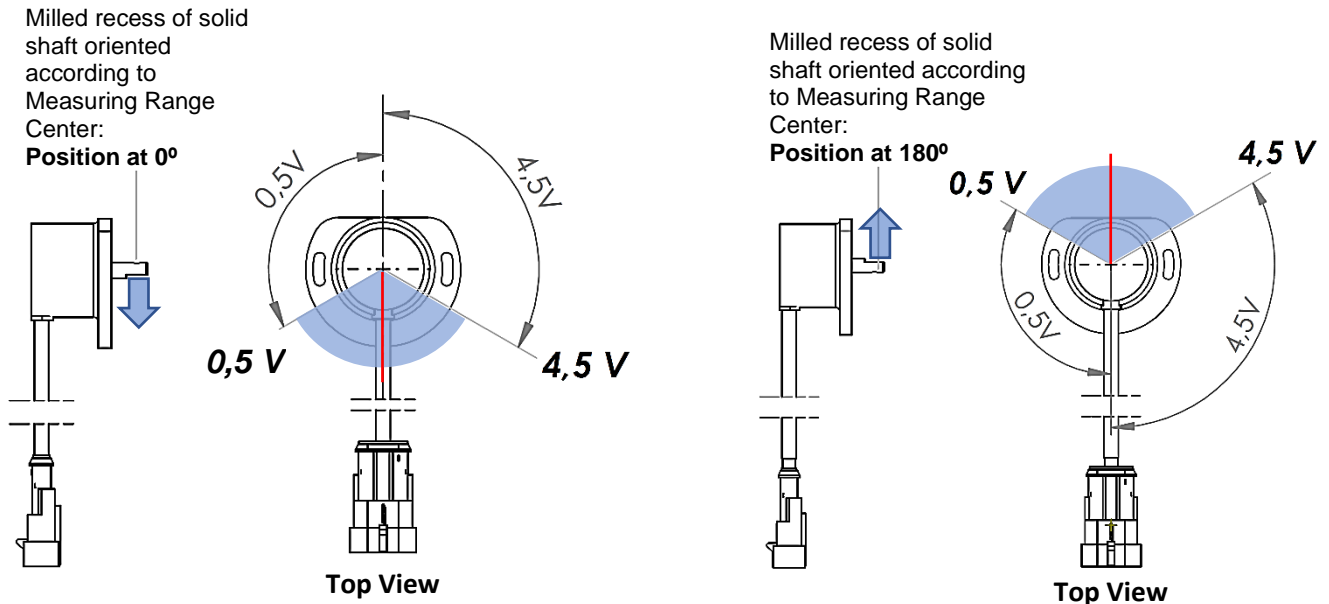


Figure 5 – Referencing the solid shaft according to the Measuring Range Center

Sometimes, it's interesting to know the signal magnitude precisely in the Measuring Range Center, as shown in Fig. 6, below.

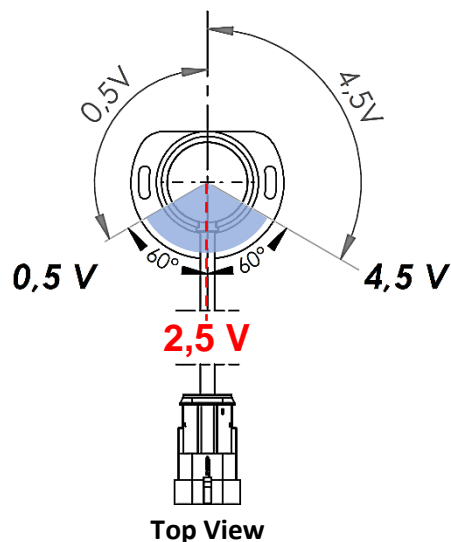


Figure 6 – Signal magnitude in the Measuring Range Center

The signal magnitude in the Measuring Range Center is calculated through the Equation 1, as follows.

$$\text{signal magnitude (Measur. Range Center)} = \left(\frac{\text{Signal}_{\max} - \text{Signal}_{\min}}{2} \right) + \text{Signal}_{\min} \quad (\text{Eq. 1})$$

CODE 5 – MEASURING RANGE

The **MEASURING RANGE** is the linear output region of the sensor signal (useful signal zone). In it occurs the proportional variation of the signal in relation to the sensor shaft movement. The Measuring Range has 2 segments, both referenced from the Center of Measuring Range. In addition to the example given in Fig. 4 (circular housing), see the Measuring Range in the Fig. 7, below (this time for the rectangular housing).

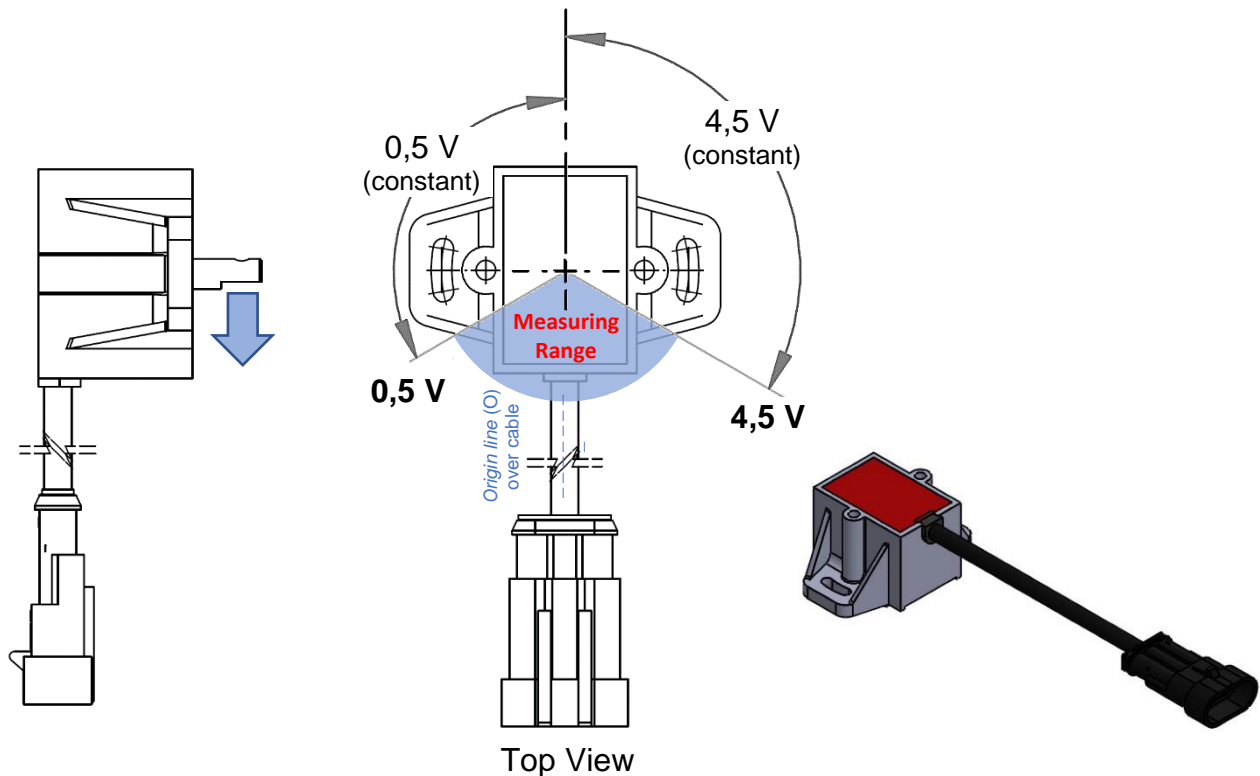


Figure 7 – Representation of Measuring Range

The measuring range is fully programmable for any condition between the minimum (0 a 18°) and maximum (0 a 360°).

Conceptual Examples

- 120° Measuring Range: 2 segments of 60° having as axis of symmetry on the Measuring Range Center (acc. to Code 4; Fig. 4 and 6).
- 60° Measuring Range: 2 segments of 30° having as axis of symmetry on the Measuring Range Center.

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Codification examples and meaning

- **ASBR US A 000 120 A 1S 00**

Signal Increment Direction = Counterclockwise

Measuring Range Center = 0° (coincident with the sensor output cable)

Measuring Range = 120° (2 segments of 60°)

Output Type = "A" (0,5 V a 4,5 V)

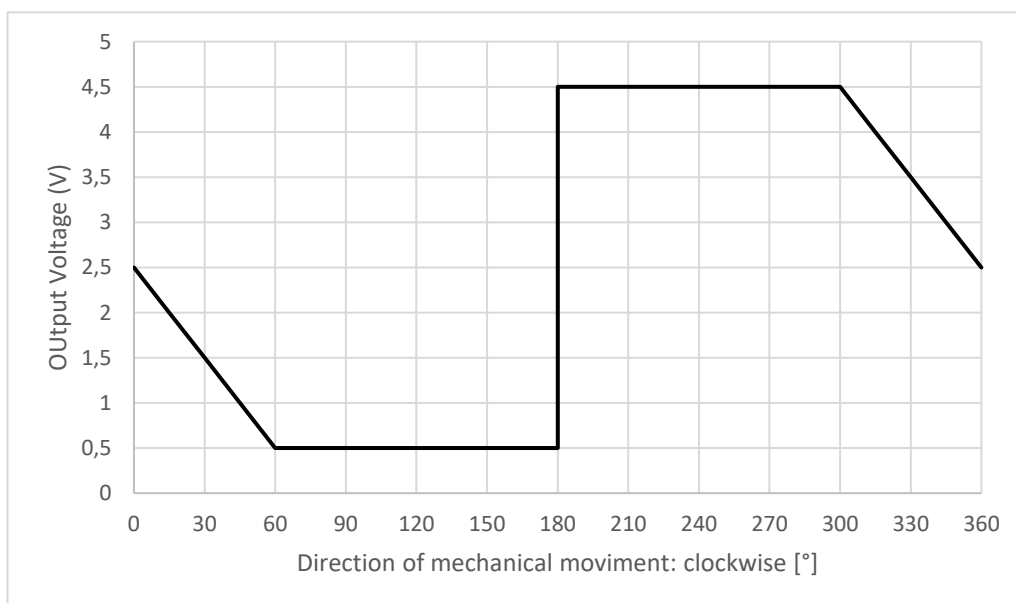
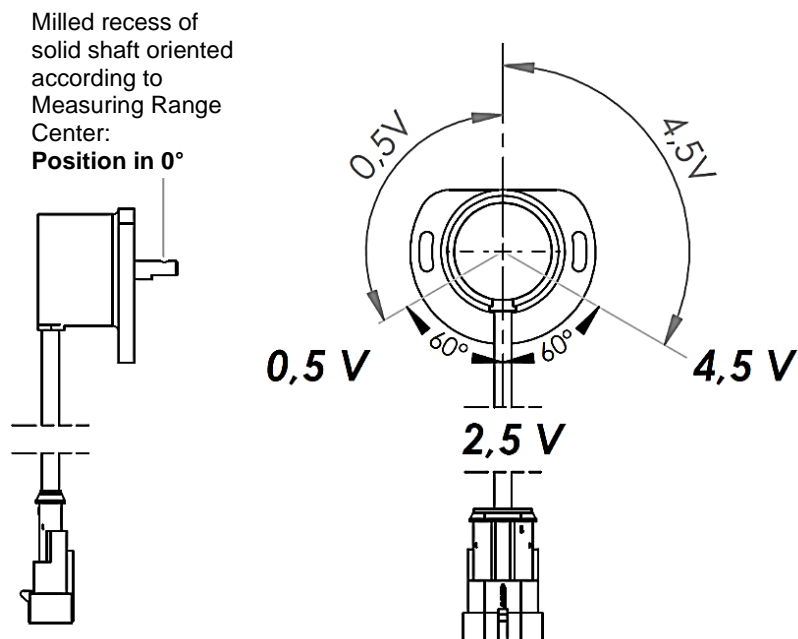


Figure 8 – Representation for the codification ASBR US A 000 120 A 1S 00

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- **ASBR US H 180 120 A 1S 00**

Signal Increment Direction = Clockwise

Measuring Range Center = 180° (symmetrical opposite with the sensor output cable)

Measuring Range = 120° (2 segments of 60°)

Output Type = "A" (0,5 V a 4,5 V)

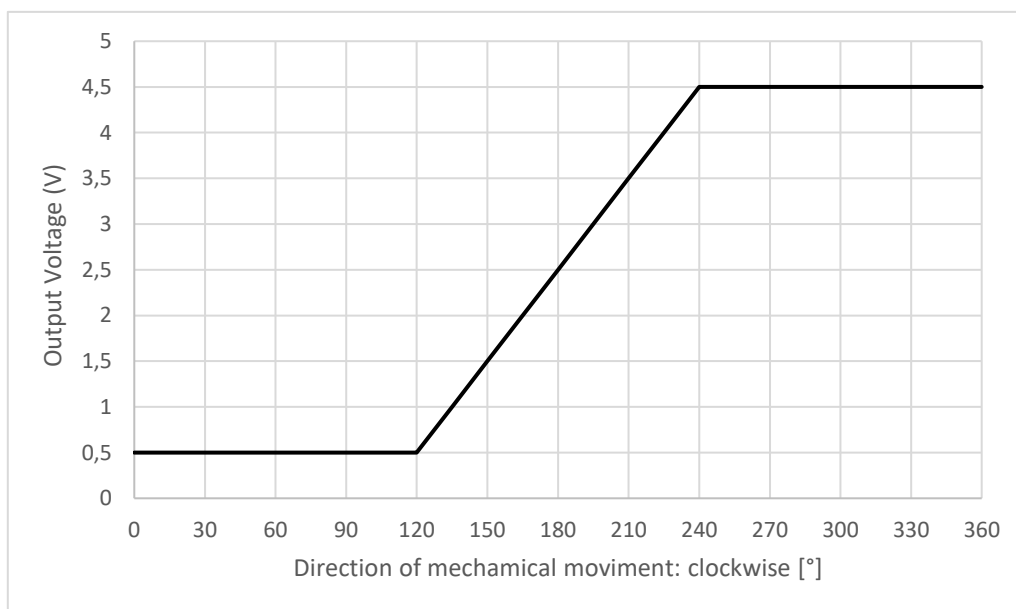
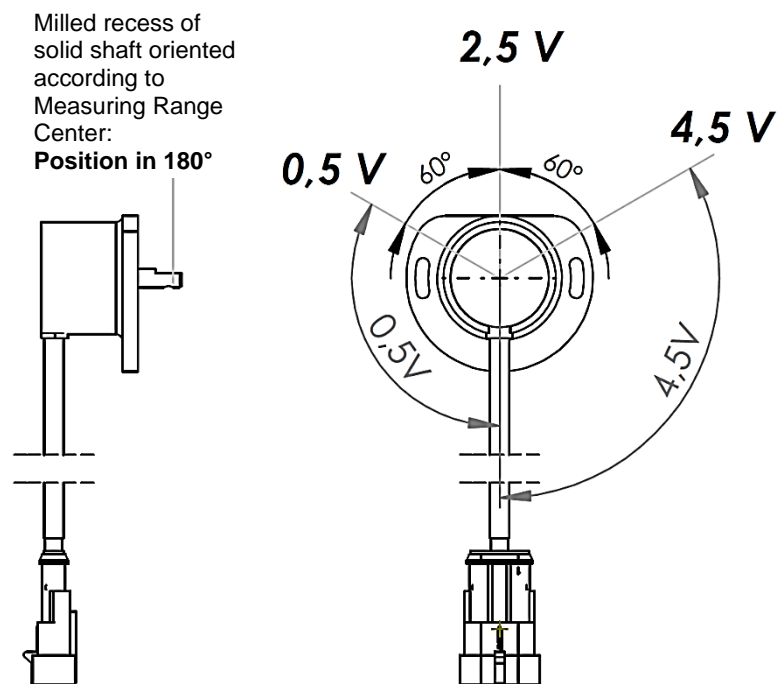


Figure 9 – Representation for the codification ASBR US H 180 120 A 1S 00

CODE 6 – OUTPUT TYPE

Regarding to the type of output signal, the angular sensor has 2 options.

- Output Voltage
 - A: 0,5 a 4,5 V
 - B: 0 a 5,0 V
- Output Current: 4 a 20mA

Other amplitudes are available on request, as the output types are fully programmable.

EXAMPLES OF CHARACTERISTIC CURVES*

*Other curves on demand

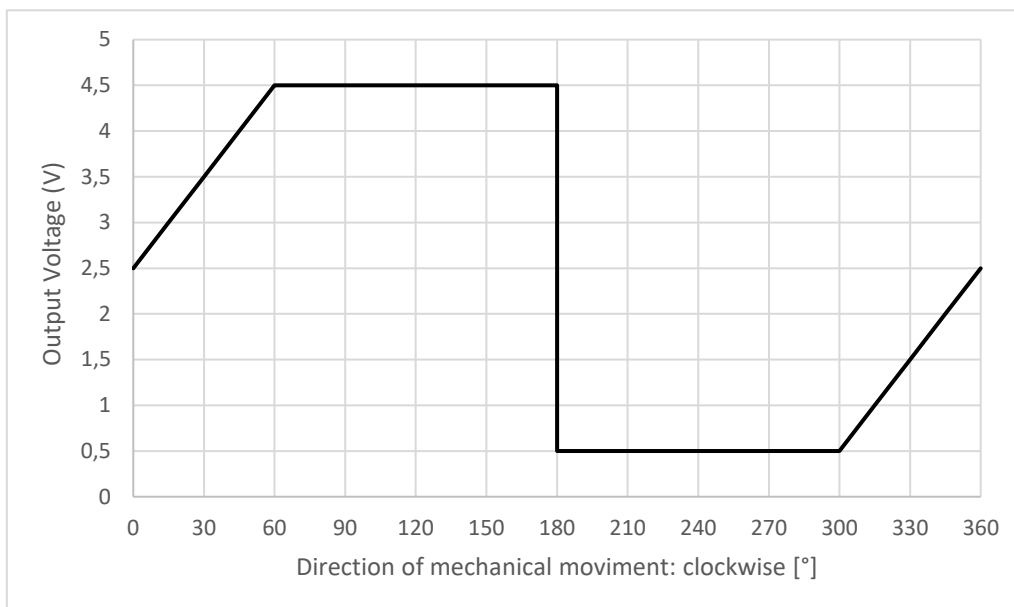


Figure 10 – Measuring Range of 120° with Center in 0°, Signal Increment Direction: clockwise (0,5-4,5 V)

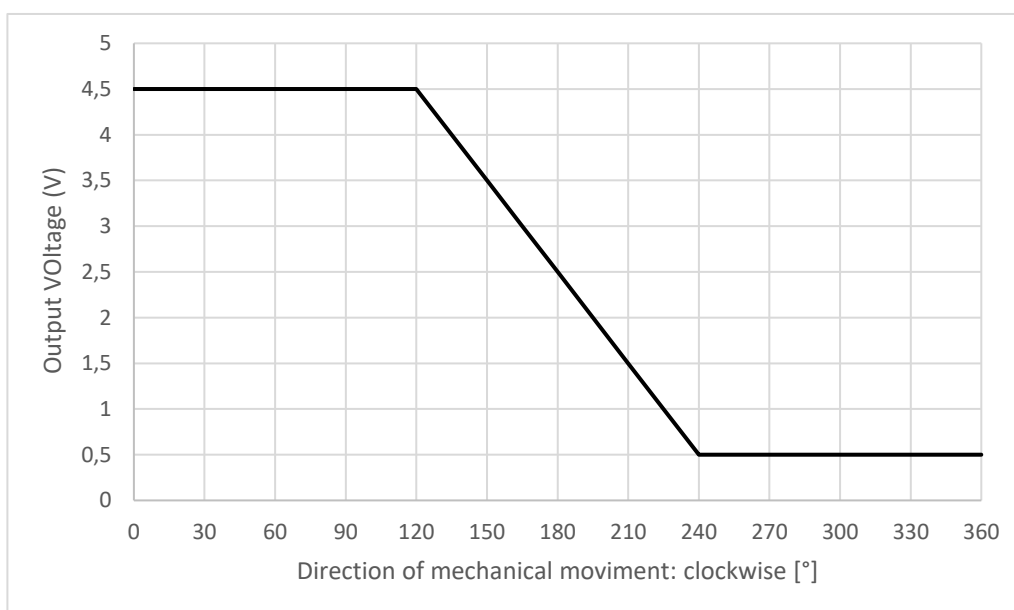


Figure 11 – Measuring Range of 120° with Center in 180°, Signal Increment Direction: counterclockwise (0,5-4,5 V)

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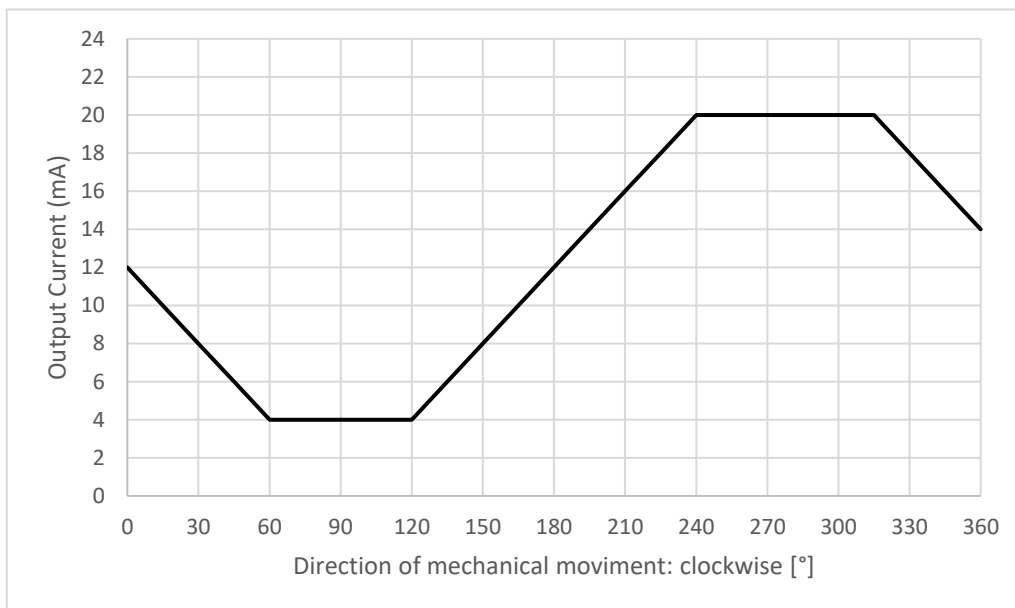


Figure 12 – Measuring Range of 120° with Center in 0°, Signal Increment Direction: counterclockwise (and Measuring Range Center 180°, signal increment direction: clockwise), mirrored double-curve (trapezoidal), 4-20 mA

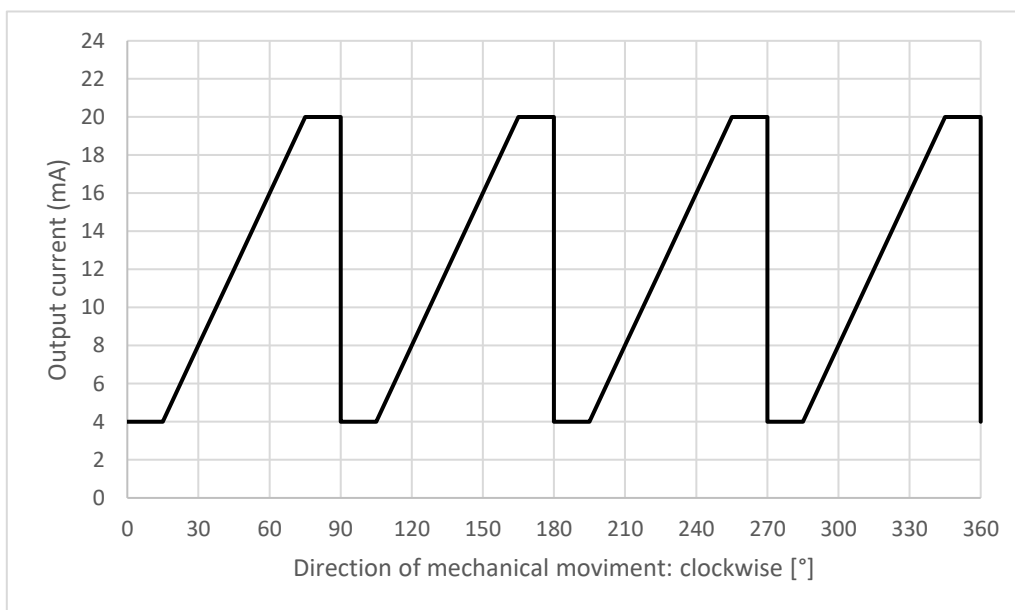


Figure 13 – Measuring Range of 60° with Center in 45°, 135°, 225° and 315°, four module (4 curves), Signal Increment Direction: clockwise, 4-20 mA

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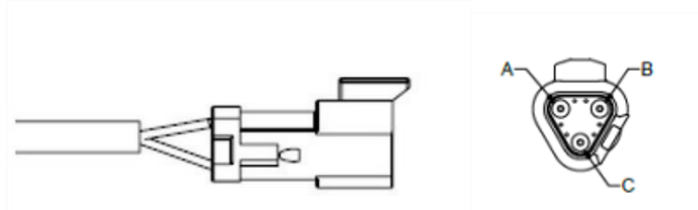


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PINOUT

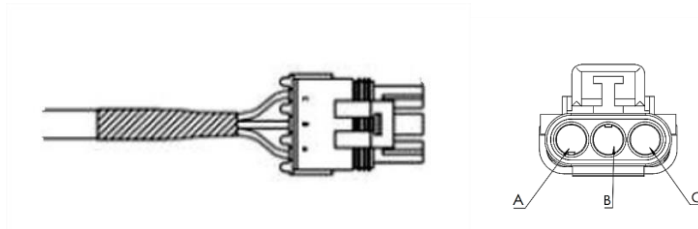
CODE 8 – CONNECTOR

- N – Deutsch Male**



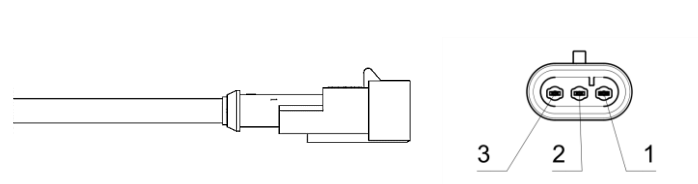
Pin	Function
A	Channel A+
B	GND
C	VCC

- P – Delphi Male**



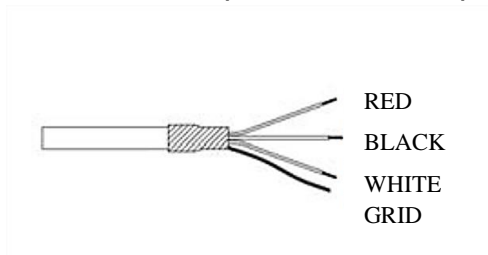
Pin	Function
A	VCC
B	GND
C	Channel A+

- S – Superseal Male**



Pin	Function
1	GND
2	VCC
3	Channel A+

- 0 – Cabo (without connector)**



Color	Function
Black	GND
Red	VCC
White	Channel A+



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